

Article ID: 1000-5641(2014)06-0012-05

Biharmonic hypersurfaces with at most two distinct principal curvatures in \mathbb{E}_s^{n+1}

YANG Chao, LIU Jian-cheng

(College of Mathematics and Statistics, Northwest Normal University, Lanzhou 730070, China)

Abstract: In this paper, we studied biharmonic hypersurfaces of pseudo-Euclidean space \mathbb{E}_s^{n+1} with at most two distinct principal curvatures. Assume the shape operator is diagonalizable, we proved that such hypersurfaces are minimal.

Key words: pseudo-Euclidean space; biharmonic hypersurface; shape operator; diagonalizable

CLC number: O 186.12 **Document code:** A

DOI: 10.3969/j.issn.1000-5641.2014.06.003

\mathbb{E}_s^{n+1} 中具有至多两个不同主曲率的 2-调和超曲面

杨 超, 刘建成

(西北师范大学 数学与统计学院, 兰州 730070)

摘要: 研究了伪欧氏空间 \mathbb{E}_s^{n+1} 中具有至多两个不同主曲率的 2-调和超曲面. 在假设形状算子可对角化的前提下, 证明了这样的超曲面是极小的.

关键词: 伪欧氏空间; 2-调和超曲面; 形状算子; 可对角化

0 Introduction

Let $x : M_r^m \rightarrow \mathbb{E}_s^n$ be an isometric immersion of an m -dimensional submanifold M_r^m of a pseudo-Euclidean space \mathbb{E}_s^n . Denote by \vec{H} and Δ the mean curvature vector field of M_r^m and the Laplace operator of M_r^m with respect to the induced metric. The submanifold M_r^m is said to be *biharmonic* if it satisfies the equation

$$\Delta \vec{H} = 0. \quad (1)$$

If the mean curvature vector field \vec{H} of the submanifold M_r^m vanishes identically, then M_r^m is called minimal. Clearly, every minimal submanifold of \mathbb{E}_s^n satisfies (1).

收稿日期: 2013-11

基金项目: 国家自然科学基金(11261051; 11171246); 甘肃省高等学校基本科研业务费资助项目

第一作者: 杨超, 女, 硕士研究生, 研究方向为微分几何. E-mail: yc963852@126.com

第二作者: 刘建成, 男, 教授, 研究方向为整体微分几何与几何分析. E-mail: liujc@nwnu.edu.cn

As remarked, minimal submanifolds are biharmonic ones. Conversely, the natural question is whether any biharmonic submanifold is minimal. In fact, [1-3] gave examples of nonminimal biharmonic surfaces in pseudo-Euclidean spaces.

However, biharmonicity implies minimality in some special cases. Indeed, it was proved in [3] that any biharmonic surface in \mathbb{E}_s^3 ($s = 1, 2$) is minimal. It was shown in [4] that every biharmonic hypersurface M_r^3 of \mathbb{E}_s^4 ($s = 0, 1, 2, 3, 4$) whose shape operator is diagonal is minimal.

Naturally, we want to consider the same problem in n -dimensional pseudo-Euclidean space \mathbb{E}_s^n ($s = 0, 1, \dots, n$). In this paper, we study the minimality of biharmonic hypersurface M_r^n with at most two distinct principal curvatures in $(n+1)$ -dimensional pseudo-Euclidean space \mathbb{E}_s^{n+1} , and prove the following theorem.

Theorem *Let M_r^n be a nondegenerate biharmonic hypersurface with at most two distinct principal curvatures of the $(n+1)$ -dimensional pseudo-Euclidean space \mathbb{E}_s^{n+1} . Assume that the shape operator of M_r^n is diagonalizable. Then M_r^n must be minimal.*

Remark A shape operator of a Riemannian submanifold is always diagonalizable, but for pseudo-Riemannian submanifolds, there may be other forms for A (cf. [5]).

1 Preliminaries

Let $x : M_r^n \rightarrow \mathbb{E}_s^{n+1}$ be an isometric immersion of a hypersurface M_r^n ($r = 0, 1, \dots, n$) in \mathbb{E}_s^{n+1} ($s = 0, 1, \dots, n+1$), $r \leq s$. The hypersurface M_r^n can itself be endowed with a Riemannian or a pseudo-Riemannian metric structure, depending on whether the metric induced on M_r^n from the pseudo-Riemannian space \mathbb{E}_s^{n+1} , is positive-definite or indefinite.

Let ξ denote a unit normal vector field with $\langle \xi, \xi \rangle = \varepsilon$, $\varepsilon = \pm 1$. Denote by ∇ and $\tilde{\nabla}$ the Levi-Civita connections of M_r^n and \mathbb{E}_s^{n+1} respectively. For any vector fields X, Y tangent to M_r^n , the Gauss formula is given by

$$\tilde{\nabla}_X Y = \nabla_X Y + h(X, Y)\xi,$$

where h is the scalar-valued second fundamental form. If we denote by A the shape operator of M_r^n associated to ξ , the Weingarten formula is given by

$$\tilde{\nabla}_X \xi = -A(X),$$

where $\langle A(X), Y \rangle = \varepsilon h(X, Y)$. The mean curvature vector $\vec{H} = H\xi$ with $H = \frac{1}{n}\varepsilon \text{tr} A$, determines a well defined normal vector field to M_r^n in \mathbb{E}_s^{n+1} . The Codazzi and Gauss equations are given by (cf. [5])

$$(\nabla_X A)Y = (\nabla_Y A)X, \quad (2)$$

$$R(X, Y)Z = \langle A(Y), Z \rangle A(X) - \langle A(X), Z \rangle A(Y), \quad (3)$$

where

$$R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z. \quad (4)$$

A hypersurface M_r^n of \mathbb{E}_s^{n+1} is said to be biharmonic, if

$$\Delta \vec{H} = 0.$$

The condition is equivalent to (cf. [1])

$$\Delta \vec{H} = \{2A(\nabla H) + n\varepsilon H(\nabla H)\} + \{\Delta H + \varepsilon H \operatorname{tr} A^2\} \xi = 0.$$

By comparing the vertical and horizontal parts of the above equation, this is equivalent to the conditions

$$A(\nabla H) = -\frac{n}{2}\varepsilon H(\nabla H), \quad (5)$$

$$\Delta H + \varepsilon H \operatorname{tr} A^2 = 0, \quad (6)$$

where the Laplace operator Δ acting on scalar-valued function f is given by (cf. [1])

$$\Delta f = -\sum_{i=1}^n \varepsilon_i (e_i e_i f - \nabla_{e_i} e_i f), \quad (7)$$

where $\{e_1, e_2, \dots, e_n\}$ is a local orthonormal frame of $T_p(M_r^n)$ with $\langle e_i, e_i \rangle = \varepsilon_i = \pm 1$.

2 Proof of the theorem

If H is a constant, then (6) implies that $H \operatorname{tr} A^2 = 0$. If H is zero, the result follows. Otherwise, $\operatorname{tr} A^2 = 0$ implies that $\lambda_1^2 + \lambda_2^2 + \dots + \lambda_n^2 = 0$, so $\lambda_1 = \lambda_2 = \dots = \lambda_n = 0$. Since $\operatorname{tr} A = \lambda_1 + \lambda_2 + \dots + \lambda_n = n\varepsilon H$, we obtain that $H = 0$.

Now, assume that H is not a constant, we will end up with a contradiction.

When H is not a constant, $\nabla H \neq 0$. According to (5), ∇H is an eigenvector of the shape operator A . Without loss generality, we can choose ∇H in the direction of e_1 , and therefore the shape operator of M_r^n takes the form with respect to a suitable orthonormal frame $\{e_1, e_2, \dots, e_n\}$

$$A = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix},$$

where $\lambda_1 = -\frac{n}{2}\varepsilon H$. If the shape operator A has only one principal curvature, i.e.

$$\lambda_1 = \lambda_2 = \dots = \lambda_n = -\frac{n}{2}\varepsilon H,$$

then $\operatorname{tr} A = -\frac{n^2}{2}\varepsilon H$. On the other hand, $\operatorname{tr} A = n\varepsilon H$. So $-\frac{n^2}{2}\varepsilon H = n\varepsilon H$, which is a contradiction as H is not a constant.

From now on, we assume that the shape operator A has two different principal curvatures. Let us express ∇H as

$$\nabla H = \varepsilon_1 e_1(H) e_1 + \varepsilon_2 e_2(H) e_2 + \dots + \varepsilon_n e_n(H) e_n.$$

Since we choose ∇H in the direction of e_1 , it follows that

$$e_1(H) \neq 0, \quad e_2(H) = e_3(H) = \dots = e_n(H) = 0. \quad (8)$$

For any $i, j = 1, 2, \dots, n$, let $\nabla_{e_i} e_j = \sum_{k=1}^n \omega_{ij}^k e_k$. By using compatibility conditions to $\nabla_{e_k} \langle e_i, e_i \rangle = 0$ and $\nabla_{e_k} \langle e_i, e_j \rangle = 0$, we obtain

$$\omega_{ki}^i = 0, \quad \omega_{ki}^j = -\varepsilon_i \varepsilon_j \omega_{kj}^i, \quad (9)$$

for $i \neq j$ and $i, j, k = 1, 2, \dots, n$. Since $\lambda_1 = -\frac{n}{2}\varepsilon H$, we get

$$e_1(\lambda_1) \neq 0, \quad e_2(\lambda_1) = e_3(\lambda_1) = \dots = e_n(\lambda_1) = 0. \quad (10)$$

The Codazzi equation (2) for hypersurfaces implies the equations

$$\langle (\nabla_{e_i} A) e_j, e_j \rangle = \langle (\nabla_{e_j} A) e_i, e_j \rangle \text{ and } \langle (\nabla_{e_i} A) e_j, e_k \rangle = \langle (\nabla_{e_j} A) e_i, e_k \rangle.$$

A straightforward calculation gives

$$e_i(\lambda_j) = (\lambda_i - \lambda_j) \omega_{ji}^j, \quad (11)$$

$$(\lambda_i - \lambda_j) \omega_{ki}^j = (\lambda_k - \lambda_j) \omega_{ik}^j, \quad (12)$$

for distinct $i, j, k = 1, 2, \dots, n$.

We claim that $\lambda_j \neq \lambda_1$ for $j = 2, \dots, n$. Indeed, if $\lambda_j = \lambda_1$, we have from (11) that

$$0 = (\lambda_1 - \lambda_j) \omega_{j1}^j = e_1(\lambda_j) = e_1(\lambda_1),$$

which contradicts to (10).

Taking into account the fact $\lambda_j \neq \lambda_1$ for $j = 2, \dots, n$ and the assumption that the hypersurfaces M_r^n have two distinct principal curvatures, we denote $\lambda_2 = \lambda_3 = \dots = \lambda_n = \mu$ and $\mu \neq \lambda_1$. Since $H = \frac{1}{n} \varepsilon \text{tr} A$, it follows that

$$\mu = \frac{3n}{2(n-1)} \varepsilon H.$$

Consider equations (11) for $j = 1, i \neq 1$, combining (9) and (10), we get

$$\omega_{1i}^1 = \omega_{11}^i = 0, \quad i = 1, 2, \dots, n.$$

For $i = 1, j \neq 1$ in (11), combining (9) we obtain

$$\omega_{j1}^j = -\frac{3e_1(H)}{(n+2)H}, \quad \omega_{jj}^1 = \varepsilon_1 \varepsilon_j \frac{3e_1(H)}{(n+2)H}. \quad (13)$$

Using equation (12) for $i = 1, j \neq k$ and $k, j = 2, 3, \dots, n$, combining (9), we have

$$\omega_{k1}^j = \omega_{kj}^1 = 0.$$

Applying the above equations, we find that

$$\begin{aligned} \nabla_{e_1} e_1 &= 0, \quad \nabla_{e_1} e_i = \sum_{k \neq 1, i} \omega_{1i}^k e_k, \quad \nabla_{e_i} e_1 = \omega_{21}^2 e_i, \\ \nabla_{e_i} e_i &= -\varepsilon_1 \varepsilon_i \omega_{21}^2 e_1 + \sum_{k \neq 1, i} \omega_{ii}^k e_k, \quad \nabla_{e_i} e_j = \sum_{k \neq 1, j} \omega_{ij}^k e_k, \end{aligned}$$

where $\omega_{21}^2 = -\frac{3e_1(H)}{(n+2)H}$, for distinct i, j and $i, j = 2, 3, \dots, n$.

Applying Gauss equation (3) and the definition (4) of the curvature tensor to $\langle R(e_1, e_2)e_1, e_2 \rangle$, it is easy to check that

$$e_1(\omega_{21}^2) = \frac{3n^2}{4(n-1)}\varepsilon_1 H^2 - (\omega_{21}^2)^2. \quad (14)$$

Using (7), (8) and the formulas of $\nabla_{e_i} e_j$, it follows from (6) that

$$-\varepsilon_1 e_1 e_1(H) - (n-1)\varepsilon_1 \omega_{21}^2 e_1(H) + \varepsilon \frac{(n+8)n^2 H^3}{4(n-1)} = 0. \quad (15)$$

By differentiating (13) with $j = 2$ along e_1 , and using (14), we get

$$e_1 e_1(H) = \frac{(n+2)(n+5)}{9} H (\omega_{21}^2)^2 - \varepsilon_1 \frac{n^2(n+2)}{4(n-1)} H^3. \quad (16)$$

Substituting (16) into (15), combining (13), we have

$$H \left[\varepsilon_1 \frac{(n+2)(-2n+8)}{9} (\omega_{21}^2)^2 - \frac{n^2(n+2) + \varepsilon n^2(n+8)}{4(n-1)} H^2 \right] = 0,$$

and as $H \neq 0$, it follows that

$$\varepsilon_1 \frac{(n+2)(-2n+8)}{9} (\omega_{21}^2)^2 - \frac{n^2(n+2) + \varepsilon n^2(n+8)}{4(n-1)} H^2 = 0. \quad (17)$$

Acting on (17) with e_1 and using (13) and (14), then

$$\varepsilon_1 \frac{(n+2)(-2n+8)}{9} (\omega_{21}^2)^2 - \frac{n^2(n+2)(-n+10 + \varepsilon(n+8))}{12(n-1)} H^2 = 0. \quad (18)$$

Eliminating ω_{21}^2 from (17) and (18), we obtain that

$$H^2 = 0,$$

which leads to $H = 0$, a contradiction.

[References]

- [1] CHEN B Y, ISHIKAWA S. Biharmonic surfaces in pseudo-Euclidean spaces [J]. Memoirs of the Faculty of Science, Kyushu University, Series A, Mathematics, 1991, 45(2): 323-347.
- [2] ISHIKAWA S. Biharmonic W-surfaces in 4-dimensional pseudo-Euclidean space [J]. Memoirs of the Faculty of Science, Kyushu University, Series A, Mathematics, 1992, 46(2): 269-286.
- [3] CHEN B Y, ISHIKAWA S. Biharmonic pseudo-Riemannian submanifolds in pseudo-Euclidean spaces [J]. Kyushu Journal of Mathematics, 1998, 52(1): 167-185.
- [4] DEFEVER F, KAIMAKAMIS G, PAPANTONIOU V. Biharmonic hypersurfaces of the 4-dimensional semi-Euclidean space E_s^4 [J]. Journal of Mathematical Analysis and Applications, 2006, 315(1): 276-286.
- [5] O'NEILL B. Semi-Riemannian Geometry with Applications to Relativity [M]. San Diego, CA: Academic press, 1983.

(责任编辑 王善平)