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An adaptive lack of fit test for big data

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ABSTRACT

New technological advancements combined with powerful computer hardware and high-speed network make big data available. The massive sample size of big data introduces unique computational challenges on scalability and storage of statistical methods. In this paper, we focus on the lack of fit test of parametric regression models under the framework of big data. We develop a computationally feasible testing approach via integrating the divide-and-conquer algorithm into a powerful nonparametric test statistic. Our theory results show that under mild conditions, the asymptotic null distribution of the proposed test is standard normal. Furthermore, the proposed test benefits from the use of data-driven bandwidth procedure and thus possesses certain adaptive property. Simulation studies show that the proposed method has satisfactory performances, and it is illustrated with an analysis of an airline data.

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Adaptive test; asymptotic distribution; divide-and-conquer algorithm; massive dataset; model specification test

1. Introduction

The advancement and prevalence of computer technology in nearly every realm of science and daily life have enabled the collection of 'big data'. While access to such wealth of information opens the door towards new discoveries, it also poses challenges to the current statistical and computational theory and methodology. Since it is usually computationally infeasible to make inference directly for big data due to the limitation of computing power and memory space, checking model misspecifications is not an easy task.

We shall now present one motivating example. There is an airline on-time data which consists of flight arrival and departure details for all commercial flights from October 1987 to April 2008 in USA. There are 123,534,969 records and 29 variables. And it occupies 11.2GB space. Due to the highly developed transportation system of airplanes, flight delay problem has become more and more serious. An appropriate model is critical for predicting the delay probability of a flight. Suppose that a parametric model is provided according to historical experience. Naturally, before fitting the new data with the proposed model, we want to make sure whether the proposed model is appropriate or not. However, for such big data, many existing softwares have failed to handle it. Since the 'big data' problem is not only the size of the data but also the analysis of it takes a significant amount of time and computer memory. Moreover, since the samples in big datasets are typically aggregated from multiple sources (Fan, Han, & Liu, 2014), a computationally feasible and efficient lack-of-fit test is highly desirable for massive datasets.

Let (Y, \mathbf{X}) be a random variable in $\mathbb{R} \times \mathbb{R}^p$. We have observations $(y_i, \mathbf{x}_i)_{i=1}^N$ from the underlying model $E(Y|X=\mathbf{x})=m(\mathbf{x})$. In a parametric regression model, $m(\mathbf{x})$ is assumed to belong to a parametric family of known real functions $g(\mathbf{x}; \boldsymbol{\theta})$ on $\mathbb{R}^p \times \Theta$, where $\Theta \subset \mathbb{R}^q$. We want to test the null hypothesis that the parametric model is correct for a dataset, say

 $H_0: m(\mathbf{x}) = g(\mathbf{x}, \boldsymbol{\theta}_0)$ for some $\boldsymbol{\theta}_0 \in \Theta$,

against the alternative hypothesis

$$H_1: m(\mathbf{x}) \neq g(\mathbf{x}, \boldsymbol{\theta}) \text{ for all } \boldsymbol{\theta} \in \Theta.$$

A number of nonparametric smoothing-based lack-of-fit tests for small and moderate sample sizes have been proposed during the last 20 years (see González-Manteiga and Crujeiras (2013) for an overview). Among them, some kernel-based tests, such as Zheng (1996) and Hardle and Mammen (1993), are easy to implement when N is not too large. However, the quadratic time complexity and large memory greatly hamper their availability to massive data applications. The main emphasis of this paper is to overcome computational barriers of traditional tests for massive data by using divide-and-conquer (DC) algorithm.

When the data is too large to access the whole dataset once in a processor, one strategy is to divide and conquer. A DC algorithm works by recursively breaking down a big dataset into two or more subsets which are manageable and then analyse these subsets separately and combine the sub-solutions as the final one. Recently, DC strategy has been widely used in analysing massive data concerning parameters estimation of parametric regression (Battey, Fan, Liu, Lu, & Zhu, 2015;

Chen & Xie, 2014; Lin & Xi, 2011; Schifano, Wu, Wang, Yan, & Chen, 2016), nonparametric regression curve estimation (Cheng & Shang, 2015; Zhang, John, & Martin, 2013; Zhao, Cheng, & Liu, 2016) and bootstrap issue (Kleiner, Talwalkar, Sarkar, & Jordan, 2015). However, little attention has been paid to the lack-of-fit test of parametric regression models for massive data. We combine the DC method with the test statistic proposed by Zheng (1996) to solve the computational problem. We separate the data into K subsets evenly with each subset having the same sample size, n. Building test statistic based on each subsample and then averaging these test statistics to obtain the final one, the computational complexity of the test statistic is reduced from N^2 to $O(Kn^2)$ and the calculation occupies much less memory, which is quite useful for big data.

The choice of smoothing parameter inherent in smoothing-based test plays an essential role, which refers to bandwidth parameter in kernel-based tests. As criteria used for smoothing parameter selection in nonparametric estimation differ from testing, it is inappropriate to apply prevalent smoothing parameter selection approaches for nonparametric estimation in the context of nonparametric hypothesis testing. There has been a growing amount of literatures on smoothing parameter selection in testing (e.g., Eubank, Ching-Shang, & Wang, 2005; Gao & Gijbels, 2008; Guerre & Lavergne, 2005; Hart, 1997; Horowitz & Spokoiny, 2001; Kulasekera & Wang, 1997; Ledwina, 1993; Zhang, 2003a, 2003b). A popular approach is to combine the test statistics obtained from using a series of suitable bandwidth values (Guerre & Lavergne, 2005; Horowitz & Spokoiny, 2001; Zhang, 2003a), resulting in an adaptive test. For instance, Horowitz and Spokoiny (2001)'s test is a maximum test with respect to a set of bandwidth values. They obtained critical values of their test statistic by bootstrap, and thus it is rather time-consuming for big datasets. We suggest to combine the method in Horowitz and Spokoiny (2001) with the DC method to construct an adaptive and computationally feasible nonparametric lack-of-fit test.

The paper is organised as follows. Section 2 describes the test statistics and bandwidth selection procedure. Asymptotic properties are discussed. Simulation studies and a real data analysis are given in Section 3. Section 4 contains some concluding remarks. Technical proofs are provided in the Appendix.

2. Methodology

The nonparametric test proposed by Zheng (1996) combines the kernel method and the conditional moment test. The key idea is to use a kernelbased sample estimator of the conditional moment $E\{E^2(\vartheta_i|\mathbf{x}_i)f(\mathbf{x}_i)\}\$, where $\vartheta_i = y_i - g(\mathbf{x}_i;\boldsymbol{\theta}_0)$ and $f(\cdot)$ is the density function of x_i . The test statistic based on the

whole sample is

$$Z_N = \frac{1}{N(N-1)} \sum_{i=1}^N \sum_{j \neq i}^N \mathcal{K}_{h_N}(\mathbf{x}_i - \mathbf{x}_j) e_i e_j,$$

where $\mathcal{K}(\cdot)$ is a p-dimensional kernel function and $\mathcal{K}_h(\cdot) = \mathcal{K}(\cdot/h)/h^p$, h_N is the bandwidth depending on *N.* $e_i = y_i - g(\mathbf{x}_i, \hat{\boldsymbol{\theta}}_N)$, where $\hat{\boldsymbol{\theta}}_N$ is an estimator of $\boldsymbol{\theta}_0$. Denote the corresponding test based on Z_N as ZH test. Clearly, Z_N is a computation-intensive when N is large, limiting its usefulness for massive data.

We use the DC strategy to solve the problem by separating the data into K subsets evenly and make each subset have the same sample size *n*. Denote the test statistic based on the kth subset of data as V_k ,

$$V_k = \frac{1}{n(n-1)} \sum_{i=1}^n \sum_{i \neq i}^n \mathcal{K}_{h_n}(\mathbf{x}_{ik} - \mathbf{x}_{jk}) e_{ik} e_{jk},$$

where h_n is the bandwidth based on the dataset of size $n. e_{ik} = y_{ik} - g(\mathbf{x}_{ik}, \hat{\boldsymbol{\theta}}_n)$, where $\hat{\boldsymbol{\theta}}_n$ is a DC-based estimator of θ_0 (Lin & Xi, 2011). The asymptotic null mean and variance of $nh_n^{p/2}V_k$ are 0 and δ^2 according to Zheng (1996) as $h_n \to 0$ and $nh_n^p \to \infty$, where

$$\delta^{2} = 2 \int \mathcal{K}^{2}(\mathbf{u}) d\mathbf{u} \int \{\sigma^{2}(\mathbf{x})\}^{2} f^{2}(\mathbf{x}) d\mathbf{x}, \ \sigma^{2}(\mathbf{x})$$
$$= E(\varepsilon_{i}^{2} | \mathbf{x}), \ \varepsilon_{i} = y_{i} - m(\mathbf{x}_{i}).$$

A consistent estimator of δ^2 using the *k*th subset data is

$$\hat{\delta}_k^2 = \frac{2}{n(n-1)} \sum_{i=1}^n \sum_{j \neq i}^n h_n^p \mathcal{K}_{h_n}^2(\mathbf{x}_{ik} - \mathbf{x}_{jk}) e_{ik}^2 e_{jk}^2.$$

Since this test is sensitive to the bandwidth selection, a robust test is desired. Following the selection approach proposed in Horowitz and Spokoiny (2001) and Zhang (2003a), for each normalised V_k , we take the maximum of the normalised statistic with respect to a candidate set of h_n which is defined as \mathcal{H}_m . The maximum and minimum elements in \mathcal{H}_m are denoted as h_{max} and h_{min} , respectively. Suppose there are m elements in \mathcal{H}_m and m is finite. This procedure is intended to reduce the dependency of the proposed test on individual h. It makes the test suitable for a broader class of alternatives compared with the original test depending on one h, leading to an adaptive test. Our final test statistic based on K subsets data is

$$D_N = \frac{1}{K} \sum_{k=1}^K \max_{h \in \mathcal{H}_m} n h^{p/2} V_k \hat{\delta}_k^{-1}.$$

For the sake of simplifying notations, we denote $nh^{p/2}V_k\hat{\delta}_k^{-1}$ as $D_k(h)$ and the test based on D_N as DM test. $\{\max_{1 \le s \le m} D_k(h_s)\}_{k=1}^K$ can be treated as K independent identically distributed random variables. On the basis of the above discussion and some mild conditions, we can establish the limiting behaviour of D_N . The following are some assumptions needed in our theories.

Assumption 2.1: The density function $f(\mathbf{x})$ of \mathbf{X} is bounded away from 0 and has bounded first-order derivatives.

Assumption 2.2: $g(\cdot, \cdot)$ is uniformly bounded in **x** and θ and is twice continuously differentiable with respect to θ , with first- and second-order derivatives uniformly bounded in **x** and $\theta \in \Theta$.

Assumption 2.3: $\mathcal{K}(u)$ is a bounded and symmetric density function.

Assumption 2.4: The random variables ε_i are independent with $E(\varepsilon_i|\mathbf{x}_i) = 0$. We assume that $\sigma^2(\mathbf{x}_i)$, $E(\varepsilon_i^4|\mathbf{x}_i) = \sigma^4(\mathbf{x}_i)$ are uniformly bounded in *i* and have uniformly bounded first-order derivatives for all i.

Assumption 2.5: Let $\theta^* = \arg\min_{\theta \in \Theta} E\{m(\mathbf{x}) - \mathbf{x}\}$ $g(\mathbf{x}; \boldsymbol{\theta})$ for any $m(\cdot)$. For any $m(\cdot)$, $\boldsymbol{\theta}^*$ is unique and $\hat{\boldsymbol{\theta}}_n$ is the estimator of θ^* such that $\sqrt{N}(\hat{\theta}_n - \theta^*) = O_p(1)$. Under H_0 , $\theta^* = \theta_0$.

The first theorem is similar to Theorem 1 in Zhang (2003a). For notational convenience, we write the index $\max_{h \in \mathcal{H}_m} D_k(h)$ as $\max_{1 \le s \le m} D_k(h_s)$.

Theorem 2.1: Suppose Assumptions 2.1–2.5 hold. Under the null hypothesis, for a finite integer $m \ge 1$, as $h_{\text{max}} \rightarrow$ 0, $nh_{\min}^p \to \infty$, we have

$$\max_{1 < s < m} D_k(h_s) \xrightarrow{d} \max_{1 < s < m} U_s,$$

where $(U_1, ..., U_m)^T$ is a mean-zero normal random vector with a covariance matrix $\Gamma = (\gamma_{st})_{1 \leq s,t \leq m}$, with $\gamma_{st} =$ $\gamma_{ts} = \delta_{st}^2/\delta^2$,

$$\delta_{st}^2 = 2l_{st}^{p/2} \int \mathcal{K}(\mathbf{u}) \mathcal{K}(\mathbf{u}l_{st}) d\mathbf{u} \int [\sigma^2(\mathbf{x})]^2 p^2(\mathbf{x}) d\mathbf{x}$$

and $l_{st} = h_s/h_t$ for $1 \le s$, $t \le m$.

 δ^2 can be consistently estimated by $(\hat{\delta}_k^2(h_s) +$ $\hat{\delta}_k^2(h_t))/2$ and δ_{st}^2 can be consistently estimated by

$$\hat{\delta}_{st}^{2} = \frac{2}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} (h_{s}h_{t})^{p/2} \mathcal{K}_{h_{s}}(\mathbf{x}_{ik} - \mathbf{x}_{jk}) \times \mathcal{K}_{h_{t}}(\mathbf{x}_{ik} - \mathbf{x}_{jk}) e_{ik}^{2} e_{ik}^{2}.$$

The mean of $\max_{1 \le s \le m} U_s$ can be obtained by Afonja (1972). Then, we use it to approximate the mean of $\max_{1 \le s \le m} D_k(h_s)$ based on Theorem 2.1 and DasGupta (2008, Theorem 6.2). Therefore, the asymptotic null distribution of D_N can be easily got through Lindeberg-Levy central limit theorem and Slutsky's theorem.

Theorem 2.2 (Null hypothesis): Given Assumptions 1– 5, under H_0 , as $K \to \infty$, $nh^p \to \infty$, $h \to 0$, we have that

$$\sqrt{K}(D_N - \mu)/\sqrt{s^2} \xrightarrow{d} N(0, 1)$$

with

$$\mu = (2\pi)^{-1/2} \sum_{s=1}^{m} \sum_{t \neq s} \frac{(1 - \gamma_{st})}{\sqrt{2 - 2\gamma_{st}}} \Phi_{m-2}(\mathbf{0}; R_{st})$$

where $R_{st} = \{r_{s,vw,t}\}, r_{s,vw,t}$ is the partial correlation between $(U_s - U_v)$ and $(U_s - U_w)$ given $(U_s - U_t)$. $\Phi(x)$ denotes the cumulative distribution functions of the standard normal distribution. s² is the sample variance computed on $\{\max_{1 \leq s \leq m} D_k(h_s)\}_{k=1}^K$.

Theorem 2.2 reveals that the asymptotic null distribution of our test is normal under some mild conditions. Based on this theorem, we can calculate the critical value for our test. Another appealing result is that the convergence rate of D_N is $K^{-1/2}$ which can be faster than the nonparametric convergence rate $(Nh_N^{p/2})^{-1}$ of ZH test provided that *K* is large enough. The proposed test can detect against a broad class of alternatives via the above bandwidth selection procedure, and hence it is an adaptive test. And it can also accelerate the calculation of ZH test and effectively reduce the demand for memory.

For the convenience of the presentation of the next result, we denote the variance of $\max_{1 \le s \le m} D_k(h_s)$ under the null hypothesis as v^2 . The next result considers the asymptotic behaviour of D_N under the local alternative $m(\mathbf{x}) = g(\mathbf{x}; \theta^*) + K^{-1/4}l(\mathbf{x}).$

Theorem 2.3 (Local alternative): Suppose Assumptions 1-5 hold. Assume $K \to \infty$, $nh^p \to \infty$, $h \to 0$, under the local alternative,

$$\sqrt{K}(D_N - \mu)/\sqrt{s^2} \xrightarrow{d} N\left(\frac{El^2(\mathbf{X})f(\mathbf{X})}{\delta \nu}, 1\right).$$

Theorem 2.3 guarantees that the D_N test has nontrivial power against contiguous alternative of order $K^{-1/4}$. Together with Theorem 2.2, Theorem 2.3 reveals that the D_N cannot distinguish alternatives of order smaller than $K^{-1/4}$ from the null.

3. Numerical analysis

3.1. Simulation studies

In this section, we conduct a sample simulation to check the finite samples performance of the proposed DM test based on the size and power. We aim to show the advantages of our test from three perspectives which are computability, time saving and adaptiveness in terms of massive data. And the comparisons are made between ZH test, DM test and GL test, where GL test is an adaptive and asymptotic normal test proposed by Guerre and Lavergne (2005). The data is generated as in Zheng (1996). \mathbf{z}_1 and \mathbf{z}_2 are generated from the standard normal distribution. The regressors are given by $\mathbf{x}_1 = \mathbf{z}_1, \mathbf{x}_2 = (\mathbf{z}_1 + \mathbf{z}_2)/\sqrt{2}$. Two cases of error term ε are considered following the standard normal and a

Table 1. Empirical size, normal errors.

		DM		GL			ZH		
N	α	<i>K</i> 40 (100)	1	<i>c</i> 1.5	2	h ₁	h ₂	h ₃	
20,000 (4800, 7400)	1.00	1.28	6.19	1.64	0.79	0.99	0.81	0.81	
	5.00	6.08	9.77	5.30	4.55	4.68	4.82	4.49	
	10.00	11.10	14.31	10.14	9.44	9.72	9.88	9.14	
40,000 (6200, 9500)	1.00	1.23	6.22	1.52	0.72	0.97	0.99	0.63	
	5.00	5.57	9.77	5.08	4.37	4.80	5.04	4.55	
	10.00	10.69	14.37	9.96	9.35	10.11	9.91	9.33	

Percentages of rejection at 1%, 5%, 10% nominal levels.

standardised Student with five degrees of freedom distribution. The simulation is based on models which are considered in Zheng (1996) and Fan and Li (2000).

Model 0:
$$Y = 1 + X_1 + X_2 + \varepsilon$$
;
Model 1: $Y = 1 + X_1 + X_2 + bX_1X_2 + \varepsilon$, $b \in [0, 1]$;
Model 2: $Y = 1 + X_1 + X_2 + 2\sin(bX_1)\sin(bX_2) + \varepsilon$, $b \in [0, 40]$.

We treat model 0 as our null hypothesis, which assumes that the real regression model is linear. Model 1 corresponding a fixed alternative is designed to see the power of the test against high-order terms. To investigate the power of the test against a high(low) frequency fixed alternative, we consider model 2. In model 2, small(large) value of b represents low(high) frequency alternative. The kernel function is chosen to be the bivariate standard normal density function

$$\mathcal{K}(u_1, u_2) = \frac{1}{2\pi} \exp\left(-\frac{u_1^2 + u_2^2}{2}\right).$$

We choose m = 3 for multiple bandwidths and set $\mathcal{H}_m = \{0.5h, h, 2h\}$. The bandwidth h is chosen to be $c_0 n^{-1/6}$ for DM test, where $c_0 = 0.25$ is a constant in order to control the size of the test. h is set to be $0.25N^{-1/6}$ for ZH and GL test as these test statistics are constructed based on sample size N. Denote $h_1 =$ $0.125N^{-1/6}$, $h_2 = 0.25N^{-1/6}$, $h_3 = 0.5N^{-1/6}$. The penalty sequence for GL test is chosen as $c\sqrt{2 \ln m}$, where c = 1, 1.5, 2. The critical values for the three tests are based on the standard normal. For DM test when m =3, $\mu=(2\sqrt{2\pi})^{-1}(a_{12}+a_{13}+a_{23}), \ a_{st}^2=\gamma_{ss}+\gamma_{tt}-2\gamma_{st}, \ 1\leq s< t\leq 3.$ We approximate μ via estimating δ^2 and δ_{st}^2 by $(\hat{\delta}_k^2(h_s)+\hat{\delta}_k^2(h_t))/2$ and $\hat{\delta}_{st}^2$, respectively.

These three tests are compared under the same time budget as time is an important evaluation criterion for massive data analysis. For DM test, we consider two settings of (N, K), which are (20,000, 40), (40,000, 100). Under the same time budget, we choose corresponding N = 7400, 9500 for ZH test, N = 4800, 6200 for GL test. This illustrates the advantage of our test in time. Under the null hypothesis, each experiment is based on 10,000 replications and 1000 under the alternatives. What we can conclude from Tables 1 and 2 is that both ZH and DM test can control type-I error. For DM test, the approximation is more acceptable when N = 40,000, K = 100 than N = 20,000, K = 40. For GL test, there is another tuning parameter c needed to be chosen. c plays a critical role in the approximation under null hypothesis. According to the simulation results, we set c = 2 in the following power comparison experiments.

The simulation reveals that the performance of ZH test for different models varies with h. ZH(h_3) behaves the best under Model 1 and low frequency of Model 2. But it has poor performance for high-frequency model. However, $ZH(h_1)$ leads to the opposite results. $ZH(h_2)$ is the most robust. It has good performance for both of the proposed alternative models. It is difficult to find out this robust h in practical applications, while our test is capable of robustness. Figures 1 and 2 show that DM test has power closer to GL test, and $ZH(h_2)$ for model 1 and low-frequency case of model 2. Figure 3 explains that DM test has power closer to the best case of ZH test, which is obtained via the smaller h_1 under highfrequency case of model 2. DM test displays the same adaptive property as GL test. However, it requires less

Table 2. Empirical size, Student errors.

		DM		GL			ZH		
N	α	<i>K</i> 40 (100)	1	<i>c</i> 1.5	2	h ₁	h ₂	h ₃	
	1.00	1.54	6.55	1.68	0.83	0.99	1.04	0.97	
20,000 (4800, 7400)	5.00	5.65	9.81	4.87	4.07	5.09	5.27	4.45	
	10.00	10.95	14.66	9.97	9.27	10.36	10.38	9.35	
	1.00	1.00	6.65	1.65	0.83	0.96	0.89	0.85	
40,000 (6200, 9500)	5.00	5.01	10.10	5.30	4.59	4.75	4.61	4.17	
	10.00	9.54	14.93	10.38	9.72	9.61	9.06	9.11	

Percentages of rejection at 1%, 5%, 10% nominal levels.

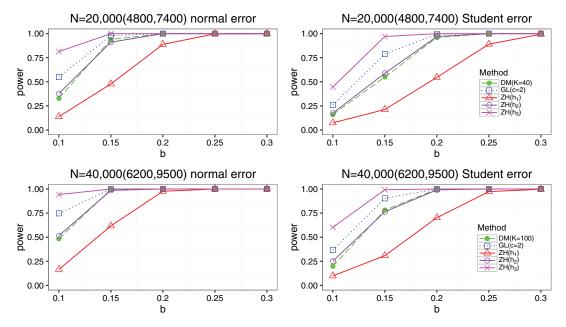


Figure 1. Comparison of power curves under model 1 of two different error terms at significant level $\alpha = 0.05$. We set (N, K) = (20,000,40), (40,000,100) for DM test. N = 4800, 6200 for GL test. N = 7400, 9500 for ZH test.

memory than GL test and ZH test under the same time budget. GL test and ZH test are either time-consuming or memory hungry which hinder the scalability to massive datasets.

Moreover, we compare DM test with ZH test based on the whole dataset to study the effect of K on the power performance. K is chosen to be {20, 40, 50} and N = 20, 000. The results under model 1 are reported in Tables 3 and 4. Model 2 follows the same trend and thus

is not included. The tables show that the power loss gets more as K gets larger for DM test compared with ZH test.

3.2. Real data analysis

In this section, we will revisit the airline on-time data for illustrating the proposed test. A flight is considered delayed when it arrived 15 or more minutes later than

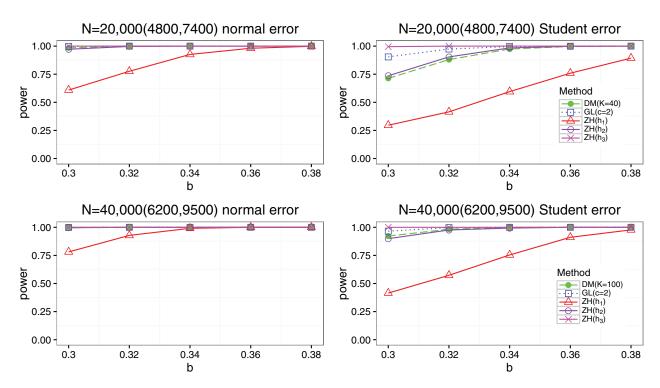


Figure 2. Comparison of power curves under low frequency of model 2 based on two different error terms at significant level $\alpha = 0.05$.

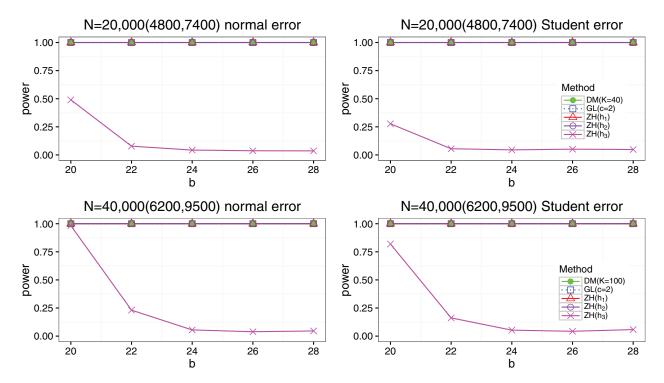


Figure 3. Comparison of power curves under high frequency of model 2 based on two different error terms at significant level $\alpha = 0.05$.

Table 3. Empirical power of DM test and ZH test based on the whole dataset when the error distribution is normal.

		DM			ZH			
b	20	<i>K</i> 40	50	h ₁	h	h		
	20	40	30	'' ₁	h ₂	h_3		
0.1	46.1	32.8	26.8	52.1	95.1	100		
0.15	99.4	94.0	89.3	98.9	100	100		
0.2	100	100	100	100	100	100		
0.25	100	100	100	100	100	100		
0.3	100	100	100	100	100	100		
0.25	100	100	100	100	100	100		

Percentages of rejection at 5% nominal levels.

Table 4. Empirical power of DM test and ZH test based on the whole dataset when the error distribution is Student.

		DM		ZH			
b	20	<i>K</i> 40	50	h ₁	h h ₂	h ₃	
0.1	20.7	16.1	13.1	22.6	59.9	96.1	
0.15	72.9	55.0	47.0	70.4	100	100	
0.2	99.5	96.1	93.7	100	100	100	
0.25	100	100	99.9	100	100	100	
0.3	100	100	100	100	100	100	

Percentages of rejection at 5% nominal levels.

the schedule. Many researchers use logistic regression to model the probability of late arrival (binary; 1 if late by more than 15 minutes, 0 otherwise; denote as y) as a function of variables may lead to flight delay. We use the logistic regression model to investigate the relationship of scheduled departure time (continuous, x_1), scheduled arrival time (continuous, x_2), distance (continuous, in thousands of miles, x_3) with late arrival. Since GL and ZH tests cannot handle such big data, only the proposed test is implemented to check the goodness of fit of this model. We get N = 120,748,239 observations after

removing the missing values. *K* is chosen to be 10,000. The bandwidth set is

$$\mathcal{H}_m = \{h_1 = 2^{-1/2}n^{1/7}, h_2 = n^{1/7}, h_3 = 2^{1/2}n^{1/7}\}.$$

The *p*-value of the proposed test is estimated as 0 which indicates that this model is inadequate to illustrate the late arrival probability. This does not come as a surprise to us, because the weather conditions and mechanical problems are also the causes of flight delay which are not included in the model.

4. Concluding remarks

In this article, we give a test aim to solve the scalability of the traditional nonparametric smoothing-based lack-of-fit test to massive datasets. We focus on two issues which are computability and smoothing parameter selection. The proposed test combines the DC procedure and a simple bandwidth selection method. Theoretically, our test has a manageable asymptotic null distribution. Under the null hypothesis, we use the mean of $\max_{1 \le s \le m} U_s$ to approximate $\max_{1 \le s \le m} D_k(h_s)$'s mean in each subset, where $(U_1, ..., U_m)^T$ is a multivariate normal distribution. To ensure the accuracy of approximation, we need to make sure that the sample size of each subset is large enough. This condition is easy to achieve for massive data. In addition, our test is advantageous to save computational time and memory space. Simulation studies verified the above theoretical properties as well as the adaptiveness.



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Appendix

In the proofs, without loss of generality, we assume q=1.

Lemma A.1: Given Assumptions 2.1–2.5. Under the null hypothesis,

$$(\hat{\delta}_k^2(h_1) + \hat{\delta}_k^2(h_2))/2$$

$$\stackrel{p}{\to} 2 \int \mathcal{K}^2(\mathbf{u}) d\mathbf{u} \int {\{\sigma^2(\mathbf{x})\}}^2 f^2(\mathbf{x}) d\mathbf{x};$$

$$\hat{\delta}_{12}^2 \stackrel{p}{\rightarrow} 2l_{12}^{p/2} \int \mathcal{K}(\mathbf{u})\mathcal{K}(\mathbf{u}l_{12})d\mathbf{u} \int {\{\sigma^2(\mathbf{x})\}^2 p^2(\mathbf{x})d\mathbf{x}}.$$

as $h \in \mathcal{H}_m$, $nh^p \to \infty$, $h \to 0$.

Proof: Similar to the proof of Lemma 3.3e of Zheng (1996), we can easily get the result of the first part. The second part is as follows:

$$\hat{\delta}_{12}^2 = \frac{2}{n(n-1)} \sum_{i=1}^n \sum_{j \neq i}^n \frac{1}{(h_1 h_2)^{p/2}} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_1}\right)$$

$$\times \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_2}\right) \varepsilon_{ik}^2 \varepsilon_{jk}^2 + o_p(1)$$

$$= 2S_n + o_p(1)$$

 S_n is a standard *U*-statistic with

$$H_n(\mathbf{z}_{ik}, \mathbf{z}_{jk}) = \frac{1}{(h_1 h_2)^{p/2}} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_1}\right) \times \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_2}\right) \varepsilon_{ik}^2 \varepsilon_{jk}^2$$

We just need to show that $E(\|H_n\|^2) = o(n)$,

$$E(\|H_{n}\|^{2})$$

$$= E\left\{\frac{1}{(h_{1}h_{2})^{p}}\mathcal{K}^{2}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{1}}\right)\mathcal{K}^{2}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{2}}\right)\varepsilon_{ik}^{4}\varepsilon_{jk}^{4}\right\}$$

$$= \int \frac{1}{(h_{1}h_{2})^{p}}\mathcal{K}^{2}\left(\frac{x_{ik} - x_{jk}}{h_{1}}\right)\mathcal{K}^{2}\left(\frac{x_{ik} - x_{jk}}{h_{2}}\right)$$

$$\times \sigma^{4}(x_{ik})\sigma^{4}(x_{jk})f(x_{ik})f(x_{jk})dx_{ik}dx_{jk}$$

$$= \int \frac{1}{h_{2}^{p}}\mathcal{K}^{2}(u)\mathcal{K}^{2}(ul_{12})$$

$$\times \sigma^{4}(x_{jk} + uh_{1})\sigma^{4}(x_{jk})f(x_{jk} + uh_{1})f(x_{jk})dudx_{jk}$$

$$= \frac{1}{h_{2}^{p}}\int \mathcal{K}^{2}(u)\mathcal{K}^{2}(ul_{12})\{\sigma^{4}(x)\}^{2}f^{2}(x)dudx + o(1)$$

$$= O(h_{2}^{-p}) = O(n(nh_{2}^{p})^{-1}) = o(n)$$

Therefore, by Lemma 3.1 of Powell, Stock, and Stoker (1989), we have proved the conclusion. \Box

Proof of Theorem 2.1

Proof: Under the null hypothesis, as

$$e_{ik} = y_{ik} - g(\mathbf{x}_{ik}; \hat{\theta}_n), \ \varepsilon_{ik} = y_{ik} - g(\mathbf{x}_{ik}; \theta_0),$$

$$u_{ik} = g(\mathbf{x}_{ik}; \hat{\theta}_n) - g(\mathbf{x}_{ik}; \theta_0),$$

so we denote $V_k = V_{1k} - 2V_{2k} + V_{3k}$, where

$$V_{1k} = \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} \frac{1}{h_n^p} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_n}\right) \varepsilon_{ik} \varepsilon_{jk};$$

$$V_{2k} = \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} \frac{1}{h_n^p} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_n}\right) \varepsilon_{ik} u_{jk};$$

$$V_{3k} = \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} \frac{1}{h_n^p} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_n}\right) u_{ik} u_{jk};$$

Then,

$$\max_{1 \le s \le m} D_k(h_s) = \max_{1 \le s \le m} nh_s^{p/2} V_k \hat{\delta}_k^{-1}$$

$$= \max_{1 \le s \le m} nh_s^{p/2} V_{1k} \hat{\delta}_k^{-1} - 2 \max_{1 \le s \le m} nh_s^{p/2} V_{2k} \hat{\delta}_k^{-1}$$

$$+ \max_{1 \le s \le m} nh_s^{p/2} V_{3k} \hat{\delta}_k^{-1}$$

$$= \max_{1 \le s \le m} D_{1k}(h_s) + \max_{1 \le s \le m} D_{2k}(h_s)$$

$$+ \max_{1 \le s \le m} D_{3k}(h_s)$$

Since $\hat{\delta}_k \stackrel{p}{\to} \delta$ based on Lemma A.1, we denote $D^*(h_s) = nh_s^{p/2}V_{1k}\delta^{-1}$. We just need to show

(a)
$$(D^*(h_1), \dots, D^*(h_m))^T \xrightarrow{d} N_m(\mathbf{0}, \Gamma)$$
, where $\Gamma = (\gamma_{st})_{1 \le s, t \le m}$;

$$= (\gamma_{st})_{1 \le s, t \le m};$$
(b) $\max_{1 \le s \le m} D_{2k}(h_s) = o_p(1); \max_{1 \le s \le m} D_{3k}(h_s) = o_p(1).$

Then, the main results of Theorem 2.1 can be obtained directly via Slutsky's theorem and Continuous Mapping theorem.

(a) Choose m = 2 as an illustration, for every $\mathbf{c} = (c_1, c_2)^T \in \mathbb{R}^2$, we have

$$\begin{split} c_{1}h_{1}^{p/2}V_{1k}(h_{1}) + c_{2}h_{2}^{p/2}V_{1k}(h_{2}) \\ &= \frac{1}{n(n-1)}\sum_{i=1}^{n}\sum_{j\neq i}^{n}\left\{\frac{c_{1}}{h_{1}^{p/2}}\mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{1}}\right)\right. \\ &+ \left.\frac{c_{2}}{h_{2}^{p/2}}\mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{2}}\right)\right\}\varepsilon_{ik}\varepsilon_{jk} \end{split}$$

 $c_1 h_1^{p/2} V_{1k}(h_1) + c_2 h_2^{p/2} V_{1k}(h_2)$ is a *U*-statistic with kernel $H_n = H_{n1} + H_{n2}$, where $H_{n1} = c_1 h_1^{-p/2} \mathcal{K}(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_1}) \varepsilon_{ik} \varepsilon_{jk}$, $H_{n2} = c_2 h_2^{-p/2} \mathcal{K}(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_2}) \varepsilon_{ik} \varepsilon_{jk}$.

By checking the conditions in Theorem 1 of Hall (1984) via the same way with Zheng (1996), we have

$$\frac{nc_1h_1^{p/2}V_{1k}(h_1) + nc_2h_2^{p/2}V_{1k}(h_2)}{\sqrt{2E(H_n^2)}} \xrightarrow{d} N(0, 1).$$

So there is a $\Gamma = \begin{bmatrix} \gamma_{11} & \gamma_{12} \\ \gamma_{21} & \gamma_{22} \end{bmatrix}$, where $(U_1, U_2)^T \sim N_2(\mathbf{0}, \Gamma)$ such that $\mathbf{c}^T [D^*(h_1), D^*(h_2)]^T \xrightarrow{d} \mathbf{c}^T (U_1, U_2)^T$ for every $\mathbf{c} = (c_1, c_2)^T \in \mathbb{R}^2$. By Cramer-Wold device, we have $[D^*(h_1), D^*(h_2)]^T \xrightarrow{d} N_2(\mathbf{0}, \Gamma)$.

Next, we determine the entries of covariance matrix Γ . Denote $(\mathbf{x}_1 - \mathbf{x}_2)/h_1 = \mathbf{u}$, $l_{12} = h_1/h_2$, we have

$$EH_{n1}^2 = c_1^2 \delta^2 / 2 + o(1), \ EH_{n2}^2 = c_2^2 \delta^2 / 2 + o(1).$$

and

 $EH_{n1}H_{n2}$ $=c_1c_2E\left\{\frac{1}{h_1^{p/2}h_2^{p/2}}\mathcal{K}\left(\frac{\mathbf{x}_1-\mathbf{x}_2}{h_1}\right)\right\}$ $\times \mathcal{K}\left(\frac{\mathbf{x}_1 - \mathbf{x}_2}{h_2}\right) \varepsilon_1^2 \varepsilon_2^2$ $= \frac{c_1 c_2}{h_1^{p/2} h_2^{p/2}} E \left\{ \mathcal{K} \left(\frac{\mathbf{x}_1 - \mathbf{x}_2}{h_1} \right) \mathcal{K} \left(\frac{\mathbf{x}_1 - \mathbf{x}_2}{h_2} \right) \right\}$ $\times E(\varepsilon_1^2|x_1)E(\varepsilon_2^2|x_2)$ $= \frac{c_1 c_2}{h_1^{p/2} h_2^{p/2}} \int \mathcal{K}\left(\frac{\mathbf{x}_1 - \mathbf{x}_2}{h_1}\right) \mathcal{K}\left(\frac{\mathbf{x}_1 - \mathbf{x}_2}{h_2}\right)$ $\times \sigma^2(\mathbf{x}_1)\sigma^2(\mathbf{x}_2) f(\mathbf{x}_1) f(\mathbf{x}_2) d\mathbf{x}_1 d\mathbf{x}_2$ $= \frac{c_1 c_2}{h_1^{p/2} h_2^{p/2}} \int \mathcal{K}(\mathbf{u}) \mathcal{K}\left(\frac{\mathbf{u} h_1}{h_2}\right) \sigma^2(\mathbf{x}_2 + \mathbf{u} h_1)$ $\times \sigma^2(\mathbf{x}_2) f(\mathbf{x}_2 + \mathbf{u}h_1) f(\mathbf{x}_2) d\mathbf{u} d\mathbf{x}_2 \cdot h_1^p$ $= l_{12}^{p/2} c_1 c_2 \int \mathcal{K}(\mathbf{u}) \mathcal{K}(\mathbf{u} l_{12}) d\mathbf{u}$ $\times \int (\sigma^2(\mathbf{x}))^2 f^2(\mathbf{x}) d\mathbf{x} + o(1)$ $= c_1 c_2 \delta_{12}/2 + o(1)$

Then, $EH_n^2 = EH_{n1}^2 + EH_{n2}^2 + 2EH_{n1}H_{n2} = c_1^2\delta^2/2 + c_2^2\delta^2/2 + c_1c_2\delta_{12} + o(1)$. So,

$$\lim_{n \to \infty} Var(nc_1 h_1^{p/2} V_{1k}(h_1) + nc_2 h_2^{p/2} V_{1k}(h_2))$$

= $c_1^2 \delta^2 + c_2^2 \delta^2 + 2c_1 c_2 \delta_{12}$.

Obviously,

$$\lim_{n \to \infty} Var(c_1 D^*(h_1) + c_2 D^*(h_2))$$

$$= c_1^2 + c_2^2 + 2c_1 c_2 \delta_{12} / \delta^2$$

Then, we obtain that

$$\gamma_{11} = \gamma_{22} = 1$$
,

$$\gamma_{12} = \gamma_{21} = \frac{\delta_{12}}{\delta^2}$$

$$= \frac{l_{12}^{p/2} \int \mathcal{K}(\mathbf{u}) \mathcal{K}(\mathbf{u}l_{12}) d\mathbf{u} \int [\sigma^2(\mathbf{x})]^2 p^2(\mathbf{x}) d\mathbf{x}}{\int \mathcal{K}^2(\mathbf{u}) d\mathbf{u} \int [\sigma^2(\mathbf{x})]^2 p^2(\mathbf{x}) d\mathbf{x}}$$

Similar result can be derived for m > 2 with $l_{st} =$ h_s/h_t

$$\gamma_{st} = \gamma_{ts} = \frac{\delta_{st}}{\delta^2}$$

$$= \frac{l_{st}^{p/2} \int \mathcal{K}(\mathbf{u}) \mathcal{K}(\mathbf{u}l_{st}) d\mathbf{u} \int [\sigma^2(\mathbf{x})]^2 p^2(\mathbf{x}) d\mathbf{x}}{\int \mathcal{K}^2(\mathbf{u}) d\mathbf{u} \int [\sigma^2(\mathbf{x})]^2 p^2(\mathbf{x}) d\mathbf{x}}$$

So, by continuous mapping theorem, we have

$$\max_{1\leq s\leq m} D^*(h_s) \xrightarrow{d} \max_{1\leq s\leq m} U_s.$$

(b) Since m is finite, from Lemma 3.3d in Zheng (1996) and Bonferroni inequality, we have the results of (b).

Proof of Theorem 2.2

Proof: Since

$$\begin{split} D_N &= \frac{1}{K} \sum_{k=1}^K \max_{h \in \mathcal{H}_m} n h^{p/2} V_k \hat{\delta}_k^{-1} \\ &= \frac{1}{K} \sum_{k=1}^K \max_{1 \leq s \leq m} D_{1k}(h_s) + \frac{1}{K} \sum_{k=1}^K \max_{1 \leq s \leq m} D_{2k}(h_s) \\ &+ \frac{1}{K} \sum_{k=1}^K \max_{1 \leq s \leq m} D_{3k}(h_s) \\ &= D_{1N} + \frac{1}{K} \sum_{k=1}^K \max_{1 \leq s \leq m} D_{2k}(h_s) \\ &+ \frac{1}{K} \sum_{k=1}^K \max_{1 \leq s \leq m} D_{3k}(h_s) \end{split}$$

As $K^{-1/2} \sum_{k=1}^K \max_{1 \le s \le m} D_{2k}(h_s) = o_p(1), \quad K^{-1/2} \sum_{k=1}^K \max_{1 \le s \le m} D_{3k}(h_s) = o_p(1), \text{ then the results of Theorem 2.2 follows } \sqrt{K}(D_{1N} - C_{2N})$ μ)/ $\sqrt{s^2} \stackrel{d}{\rightarrow} N(0,1)$.

We elucidate the proof based on Lindeberg-Levy central limit theorem. First, we approximate the mean $E(\max_{1 \le s \le m} D_{1k}(h_s))$ by asymptotic. Afonja (1972) presents a method for finding the mean of maximum of correlated normal variates. By using their Corollary 2, we can get the mean of $\max_{1 < s < m} U_s$ is

$$E(\max_{1 \le s \le m} U_s)$$

$$= (2\pi)^{-1/2} \sum_{s=1}^m \sum_{t \ne s} \frac{(1 - \gamma_{st})}{\sqrt{2 - 2\gamma_{st}}} \Phi_{m-2}(\mathbf{0}; R_{st})$$

with

$$R_{st} = \{r_{s,vw,t}\}; \ v, w = 1, ..., m; \ v, w \neq s$$

and $r_{s, v; w, t}$ is the partial correlation between $(U_s - U_v)$ and $(U_s - U_w)$ given $(U_s - U_t)$. $\Phi(x)$ denotes the cumulative distribution functions of the standard normal distribution.

For s^2 is a consistent estimator of variance of $\max_{1 < s < m} D_k(h_s)$, the theorem results directly follows Lindeberg-Levy central limit theorem and Slutsky's theorem as $K \to \infty$.

Proof of Theorem 2.3

Proof: Under the local alternative, denote

$$\begin{split} V_{1k} &= \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} \frac{1}{h_{n}^{p}} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{n}}\right) \varepsilon_{ik} \varepsilon_{jk}; \\ V_{2k} &= \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} \frac{1}{h_{n}^{p}} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{n}}\right) \varepsilon_{ik} u_{jk}; \\ V_{3k} &= \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} \frac{1}{h_{n}^{p}} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{n}}\right) u_{ik} u_{jk}; \\ V_{4k} &= \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{j \neq i}^{n} \frac{1}{h_{n}^{p}} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{n}}\right) \\ &\times (\varepsilon_{ik} - u_{ik}) l(\mathbf{x}_{jk}); \\ V_{5k} &= \frac{1}{n(n-1)} \sum_{i=1}^{n} \sum_{i \neq i}^{n} \frac{1}{h_{n}^{p}} \mathcal{K}\left(\frac{\mathbf{x}_{ik} - \mathbf{x}_{jk}}{h_{n}}\right) l(\mathbf{x}_{ik}) l(\mathbf{x}_{jk}); \end{split}$$

We proceed with a decomposition of

$$D_{N} = \frac{1}{K} \sum_{k=1}^{K} \max_{h \in \mathcal{H}_{m}} nh^{p/2} V_{k} \hat{\delta}_{k}^{-1}$$
$$= \frac{1}{K} \sum_{k=1}^{K} \max_{1 \le s \le m} nh_{s}^{p/2} V_{1k} \hat{\delta}_{k}^{-1}$$

$$\begin{split} &-2\frac{1}{K}\sum_{k=1}^{K}\max_{1\leq s\leq m}nh_{s}^{p/2}V_{2k}\hat{\delta}_{k}^{-1}\\ &+\frac{1}{K}\sum_{k=1}^{K}\max_{1\leq s\leq m}nh_{s}^{p/2}V_{3k}\hat{\delta}_{k}^{-1}\\ &+2K^{-1/4}\frac{1}{K}\sum_{k=1}^{K}\max_{1\leq s\leq m}nh_{s}^{p/2}V_{4k}\hat{\delta}_{k}^{-1}\\ &+K^{-1/2}\frac{1}{K}\sum_{k=1}^{K}\max_{1\leq s\leq m}nh_{s}^{p/2}V_{5k}\hat{\delta}_{k}^{-1}\\ &=D_{1N}+D_{2N}+D_{3N}+K^{-1/4}D_{4N}+K^{-1/2}D_{5N} \end{split}$$

Through tedious calculation we have, under local alternative, $s^2 \stackrel{p}{\rightarrow} v^2$ and

$$\sqrt{K}(D_N - \mu)/\sqrt{s^2}
= \sqrt{K}(D_{1N} - \mu)/\sqrt{s^2} + D_{5N}/\sqrt{s^2} + o_p(1)$$

As $nh^p \to \infty$, $h \to 0$, we have $D_{5N} \xrightarrow{p} \frac{El^2(\mathbf{X})f(\mathbf{X})}{\delta}$. Together with Theorem 2.2, we can get the results of Theorem 2.3.